

Cameras As Computing Systems

Prof. Hank Dietz

In Search Of Sensors

University of Kentucky
Electrical & Computer Engineering

Things You Already Know

- The sensor is some kind of chip
- Most can't distinguish colors
- They have lots of pixels (sensors)
- They're pretty good & getting better

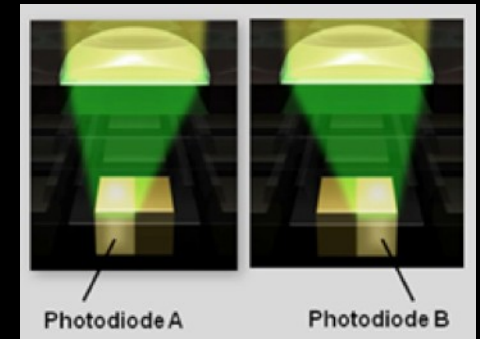
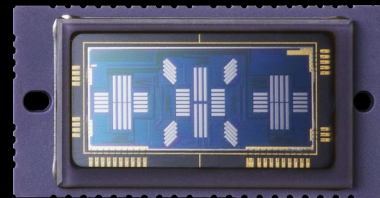
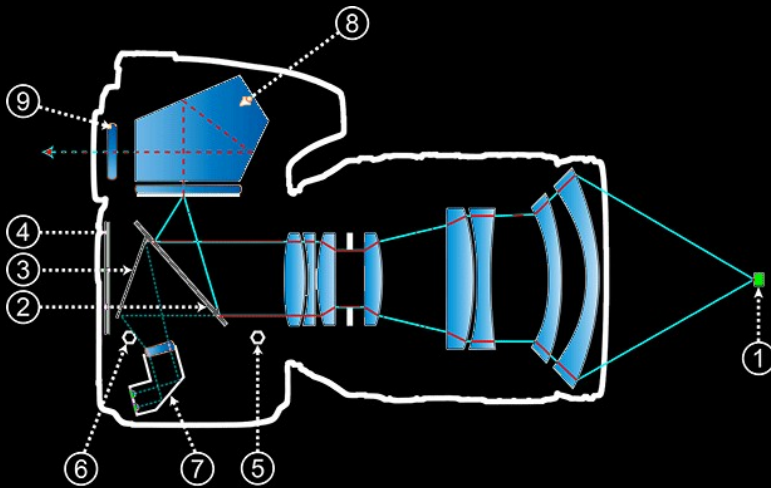
Where Is The Sensor?

- Sensor
- Shutter
- Microlens array
- CFA
- Mirror
- NIR-blocking filter
- IBIS
- PDAF
- AA filter
- Dust...?

Mirror

- Reflects light to **OVF** (Optical ViewFinder):
 - In “**mirror box**” of **SLR** (Single Lens Reflex)
 - **TLR** (Twin Lens Reflex)
- Reflects light to secondary sensors
- Moving conventional front surface mirror
- Fixed **pellical** (thin semi-transparent) mirror
(Sony's **SLT** – Single Lens **Translucent**)

PDAF?



- **Phase Detect AutoFocus** – estimate defocus direction and distance by measuring feature Separation between left/right views
- Traditionally done with separate line sensors, now can be done on main sensor using the microlens offset to separate left/right views

Anti-Dust Stuff



- Often, top layer of sensor is just glass
- Usually has an anti-static coating
- Glass far in front to diffuse dust shadows (even “**Dust-Shield**” user-installable plastic)
- Sometimes, an **ultrasonic filter** – camera can shake glass to repel dust
- Often over a sticky tape to catch dust...

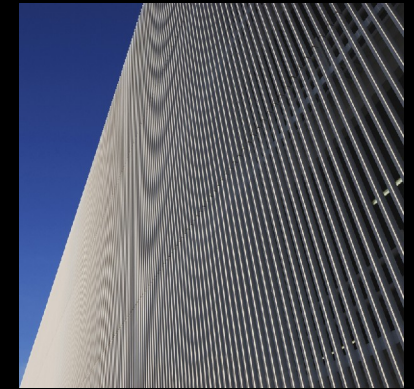
Shutter

- **Leaf** – aperture iris, but closes completely
- **Focal Plane** – a moving slit
 - 1st curtain opens
 - 2nd curtain follows closing
- Electronic shuttering methods:
 - **Solid state optical / LC** – no moving parts
 - **Global** – all sensels sampled at once
 - **Rolling** – sensels sampled in scan order

NIR-Blocking Filter

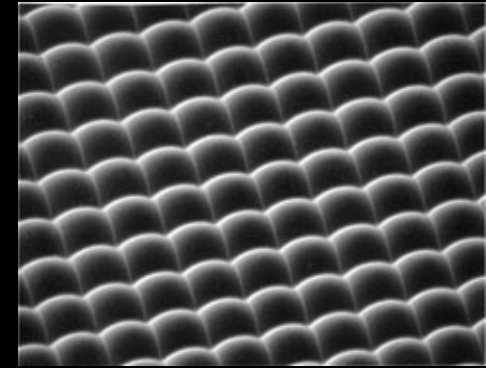
- Most image sensors strongly detect NIR
- Wavelengths from ~850nm to ~1100nm (IR is from ~8000nm to ~13000nm)
- **Hot Mirror** – **dichroic mirror** or **interference filter** that passes visible light, not (N)IR (a **Cold Mirror** is the opposite)
- Many camera NIR filters are *coatings...* which leak and often have visible color tints

Anti-Aliasing (AA) Filter



- Aka, Optical Low-Pass / Blur Filter
- Used to avoid Moire' Patterns caused by regular spacing of sensels below Nyquist
- Sensors using CFAs interpolate wrong colors
- Above Nyquist if lens resolution is poor – a 5um sensel is ~Nyquist for 50lppmm

Microlens Array



- **Fill Factor** – fraction of sensel area sensing
- Low fill factors are bad:
 - Leave gaps, breaking sampling (Nyquist)
 - Waste photons, reducing sensitivity
- **Microlens Array** – literally, a lens over each sensel area to focus light on active area
- Hard to make, simple plano-convex lenses (don't focus all light where you want it)

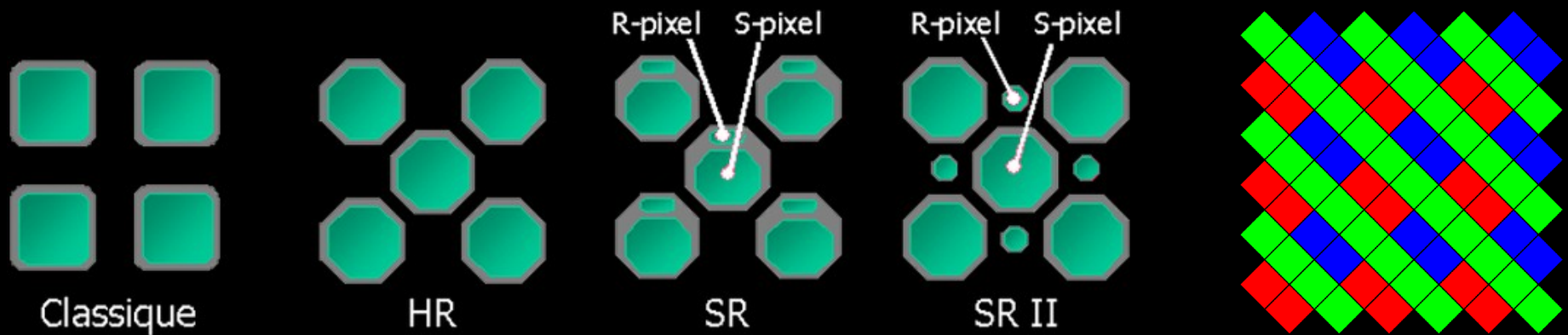
Color Filter Array (CFA)

- Color choices:
 - Bayer – [[Red, Green], [Green, Blue]]
 - Cyan, Magenta, Yellow, Green
 - Red, Green, Blue, Clear
 - Deliberately randomized, etc.
- Pattern choices:
 - Rectangular array of square sensels
 - Diagonal array of hexagonal sensels (Fuji)
 - Large or randomized color patterns

The Main Sensor

- Various technologies:
 - **CCD (Charge-Coupled Device)**
 - **CMOS** – now most common in cameras
 - **Foveon** – color by depth, stacked pixels
 - **Microbolometers** for IR, etc.
- Can be front or **back illuminated**
- ISO is a function of **quantum efficiency**, fill factor, analog gain, etc.
- **Higher sensitivity makes low ISOs hard...**

Funny-Looking From Fuji



- Fuji is trying lots of unusual layouts...
 - Fuji SuperCCD SR sensor (in S3)
 - Fuji EXR sensor (in X10)
- No other company has followed this path

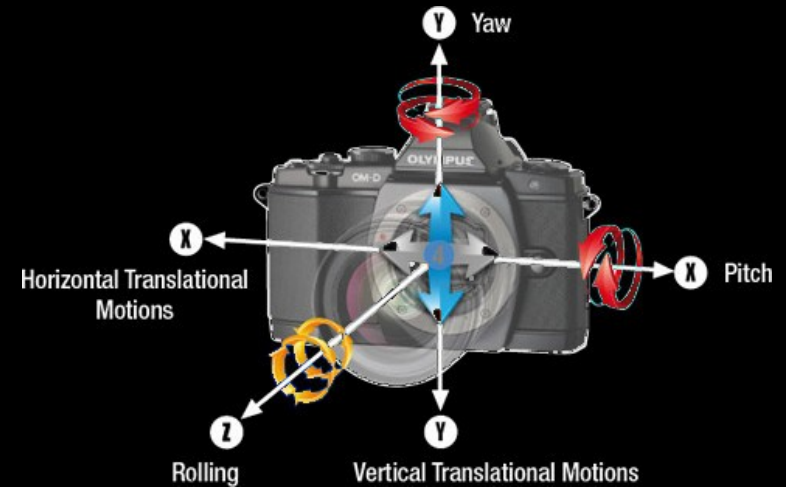
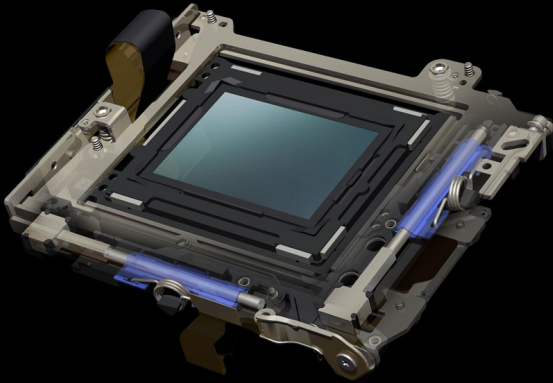
My TDCI Sensor Concept

- **TDCI (Time Domain Continuous Imaging)** – sensor doesn't actually capture images
- Each sensel has a processor *under* it (or could use **compressed sensing**)
- Asynchronously measure time for each sensel to reach a threshold (then reset)
- Sensor returns smooth waveform per sensel giving sensed EV as a function of time
- Images computed from waveforms

The Main Sensor

- Sensels are linear photon counters
- Analog values converted to 8-14 bit digital
- Interpolation of colors
 - Various algorithms... not a trivial issue
 - Color vs. resolution; handling of noise
 - Pixel/dust mapping; dark frame subtraction
- Determine & correct for black point, color
(CMS – color management system)

IBIS?



- **In Body Image Stabilization** – anti-shake by moving the sensor inside the body
- Movement to compensate computed from motion and lens focal length
- Can have from 2 to 5 axis of motion for the plate on which the sensor is mounted

Conclusion

- The sensor isn't as exposed as you think
 - Sensor cleaning not as scary as you think
 - Can change sensor stack (maxmax.com)
- Mechanical complexity is high
- Lots of differences even with same sensor –
e.g., Sony sensors in Nikon cameras