Performance and Supercomputers

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Performance is about Choices



<u>Airplane</u>	<u>Passengers</u>	<u>Range (mi)</u>	Speed (mph)
Boeing 737-100	101	630	598
Boeing 747	470	4150	610
BAC/Sud Concor	de 132	4000	1350
Douglas DC-8-50	146	8720	544

- Execution time for application
- Power / temperature / battery life
- Reliability / availability
- Cost for acceptable functionality
- Size

Response Time vs. Throughput

- Often can trade one for the other:
 Response Time: Time to complete an operation
 Throughput: Jobs completed per unit time
- Performance(X) = 1/ExecutionTime(<math>X)
- X is Performance(X)/Performance(Y) times faster than Y, also:
 - ExecutionTime(Y)/ExecutionTime(X)

For Whom The Clock Ticks

- Posix uses real, user, system time
 - Real "Wall Clock" time always ticks
 - User time while in your code
 - System time while in OS code for you
- Multiplied by #PEs in multiprocessors
- I/O time not reported under Posix
- There are really lots of timing components
 - Processor tick count register
 - OS scheduler in 1-10ms Jiffies

Running What?

- Different program, different performance
- Application (all that really matters!)
- "Toy" program
- Benchmark: representative application
- Micro Benchmark: tests a certain feature
- Synthetic Benchmark: a program written solely to perform like a particular application, but doing nothing useful
- Benchmark Suite: multiple benchmarks

Modeling Time: CPI and IPC

- CPI is clock Cycles / Instruction
- IPC is Instructions / Cycle; i.e., 1/CPI
- Program runtime is:
 (Instructions executed / Program) *
 CPI * (Clock Period)
- Really sum over all instruction types because different instructions have different CPI

An Example

Instruction Type	Execution Count	СРІ	Clock Period
A	20	10	10ns
В	10	30	10ns

- This program takes:
 - ((20*10)+(10*30))*10ns = 5us
- What can be changed to make it 4us?

What Effects What?

	Instruction Count	CPI	Clock Rate
Program (Algorithm)	Yes!	Indirectly	No!
Compiler	Yes!	Indirectly	Power?
ISA	Yes!	Yes!	Indirectly
Impl. Arch.	uOps?	Yes!	Yes!
VLSI	No!	Indirectly	Yes!

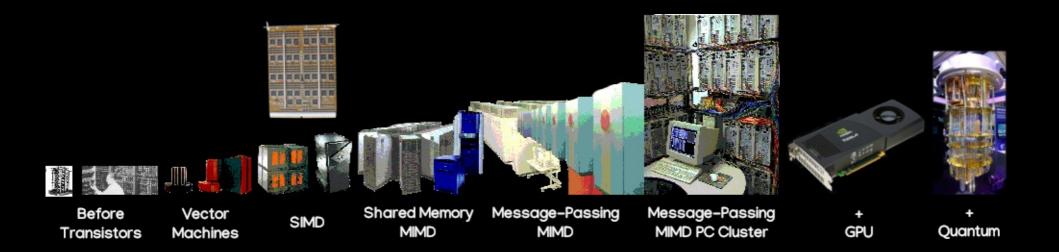
Amdahl's Law

- If 1/N time is not affected by a change, the best possible speedup is only N
- Originally for sequential overhead in parallel code, but applies for any change

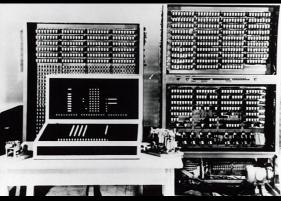
Suppose a program spends 80% of its time doing multiplies... you can't get more than a 5X speedup by improving only multiplies!

What Is A Supercomputer?

- Really two key characteristics:
 - Computer that solves big problems...
 - Performance can scale...
- The key is Parallel Processing...
 and modularity brings availability & reliability







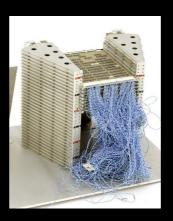




- Before cheap transistors (– 1960s)
- E.g.: ENIAC
- Faster because machines are faster than humans
- Does one operation at a time because circuitry is too expensive to do more









- Cheap transistors (1970s)
- E.g.: Cray 1
- Faster by applying the same operation to a vector of data at a time:

$$A[0..N] = B[0..N] + C[0..N]$$

Can't change parallelism width without changing all register sizes and datapaths









- Cheap chips with many transistors (1980s)
- E.g.: Thinking Machines Connection Machine
- Faster by applying the same operation to a vector of data at a time
- Modularly scalable SIMD (Single Instruction, Multiple Data) – can change parallelism simply by adding modules







- Cheap processors with custom memory
- E.g.: SGI Origin
- Faster by executing different code in parallel, using a custom shared memory to interact
- Modularly scalable MIMD (Multiple Instruction, Multiple Data) – can change parallelism simply by adding modules





- Cheap processors with custom network (1990s)
- E.g.: ASCI Red
- Faster by executing different code in parallel, using a custom messaging network to interact
- Modularly scalable MIMD (Multiple Instruction, Multiple Data) – can change parallelism simply by adding modules











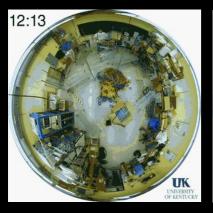




- Commodity parts and interfaces (1994)
- E.g.: Spareparticus, Beowulf, KLAT2, NAK
- Faster by executing different code in parallel, leverages commodity processors and network and also standard interfaces for custom parts
- Modularly scalable MIMD (Multiple Instruction, Multiple Data) – can change parallelism simply by adding modules

Clusters And Bigger

- Mostly from interchangeable (PC) parts...
 and mostly running some form of Linux
- Cluster or Beowulf is a parallel supercomputer with tightly coupled, homogeneous, nodes
- Farm is homogeneous, colocated, machines with a common purpose (e.g., a render farm)
- Warehouse Scale Computer is a warehouse full of racked clusters used for throughput
- Grid is many internet-connected machines
- Cloud is virtualized grid/WSCs providing services









- GPUs (Graphics Processing Units) as cheap, fast, add-in cards in cluster nodes (2010 –)
- E.g.: NAK (and most of the Top500)
- The thing(s) on video cards... SIMDish, but:
 - Lots of little SIMDs (low fanout)
 - Multithreading to hide memory latency
 - Various restrictions to simplify HW
- NVIDIA CUDA and OpenCL...
- Intel's Xeon Phi is *sort-of* a GPU, but MIMDish
- GPU(s) will be on chip with SMP cores

Types Of <u>Hardware Parallelis</u>m

- Pipeline
- Superscalar, VLIW, EPIC
- SWAR (SIMD Within A Register)
- SMP (Symmetric MultiProcessor; multi-core)
- GPU (Graphics Processing Unit)
- Cluster
- Farm / Warehouse Scale Computer
- Grid / Cloud

Auto in processor; Manual; Manual across nodes

Quantum?











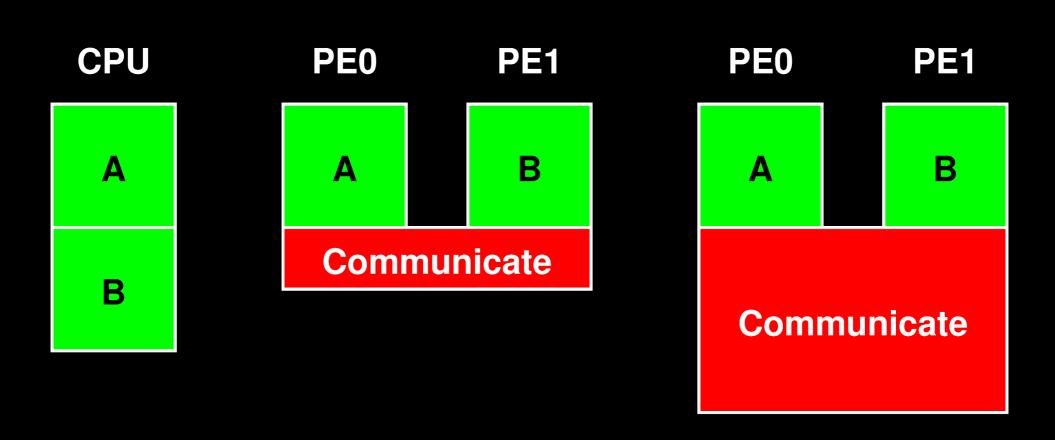


- Quantum uses QuBits rather than Bits
- Superposition allows 0, 1, or *indeterminate*
- Entangled superposed QuBits can hold a PDF over all possible values simultaneously
 - E.g., 6 QuBits can hold {0, 1, 2, ... 63}
 - Parallel processing without parallel hardware
- Reading a QuBit's value collapses superposition; you get only a single answer
- Could be the next big thing... or not

Engineering an Interconnection Network

- Parallel supercomputer nodes interact
- Bandwidth
 - Bits transmitted per second
 - Bisection Bandwidth most important
- Latency
 - Time to send something here to there
 - Harder to improve than bandwidth
- We'll just consider topology here...

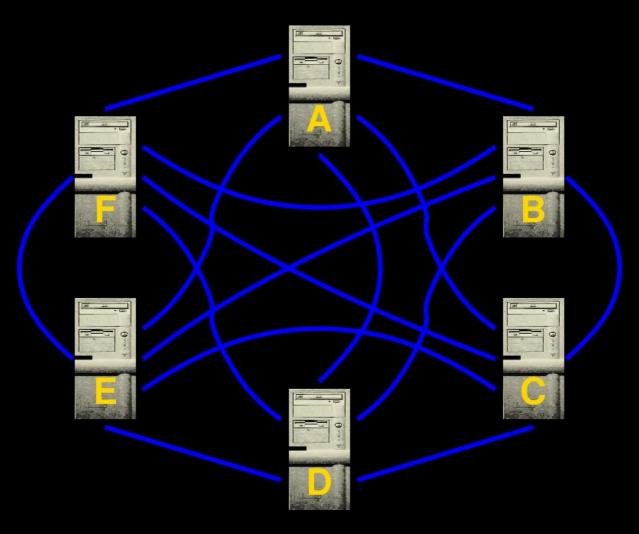
Latency Determines Smallest Useful Parallel Grain Size



No Network



Direct Fully Connected



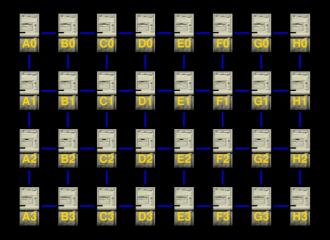
Indirect Networks

Ring: Two Physical Layouts

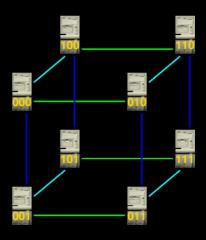




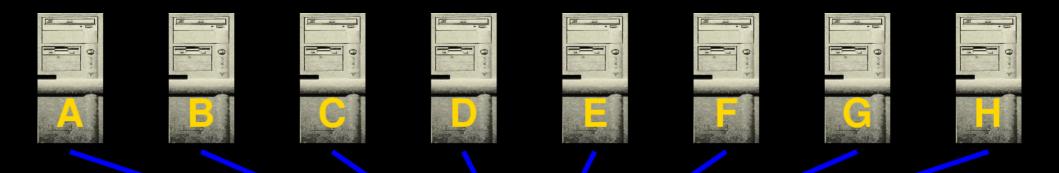
Non-Toroidal 2D Mesh



3-Cube (3D Toroidal Mesh)

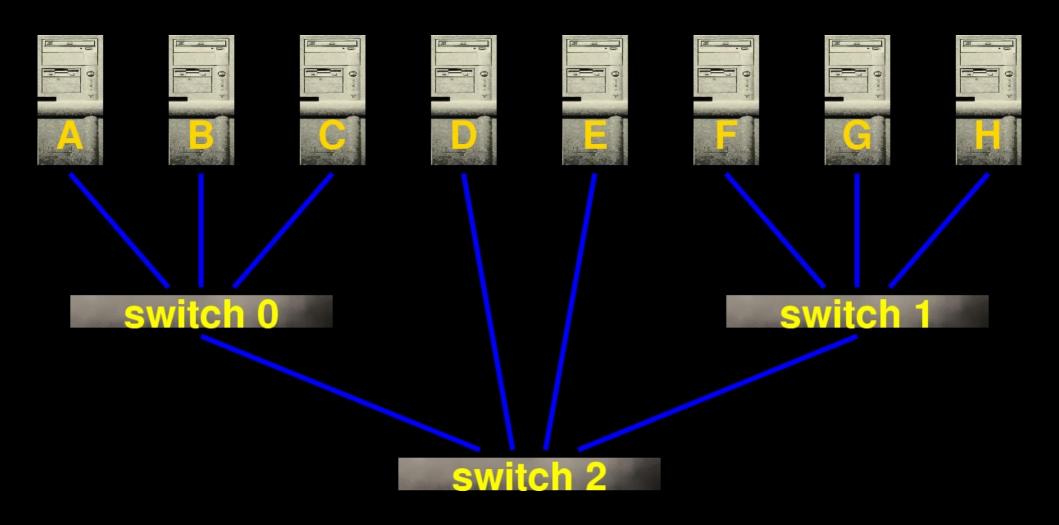


Simple Switch (8-Port)

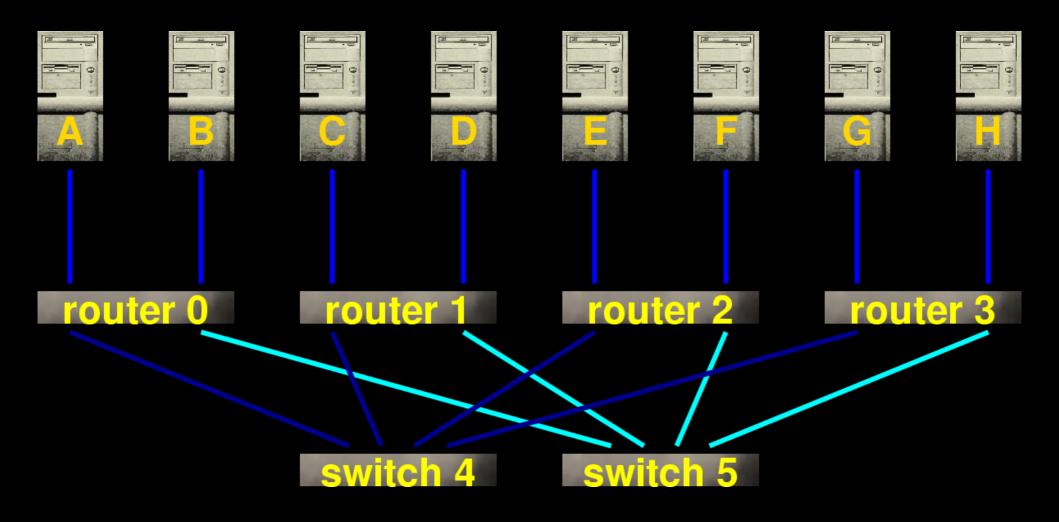


switch

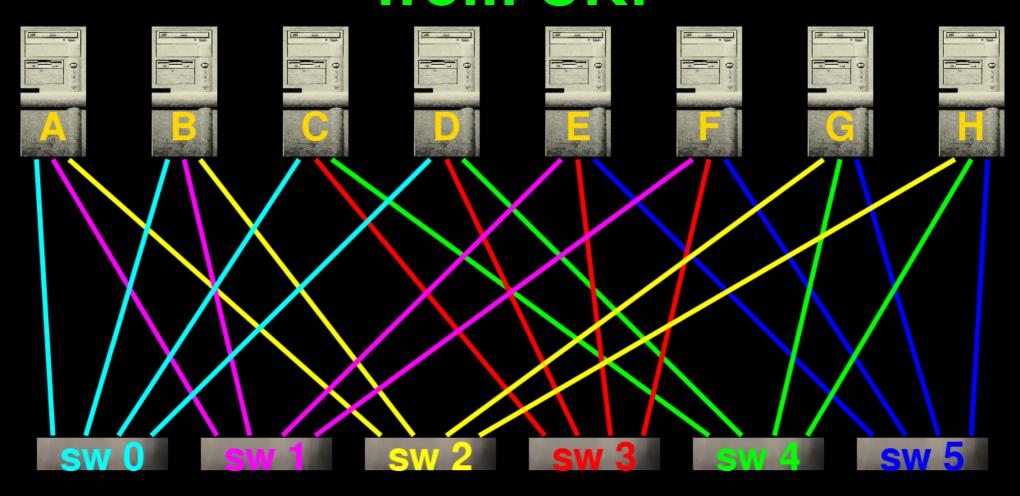
A Maximum-Bisection Tree



Fat Tree



Flat Neighborhood Network... from UK!





A Little Progress



A GFLOPS is 1 Billion {+,*} per second

1992 MasPar MP1 \$1,000,000 / GFLOPS

2000 KLAT2 \$650 / GFLOPS

2003 KASY0 \$84 / GFLOPS

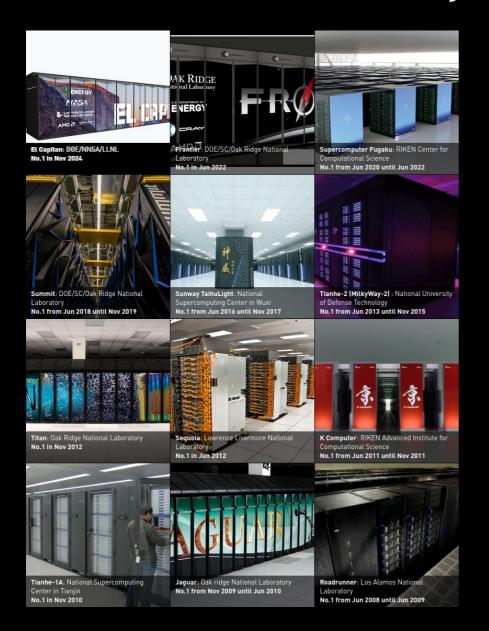
2010 NAK \$0.65 / GFLOPS

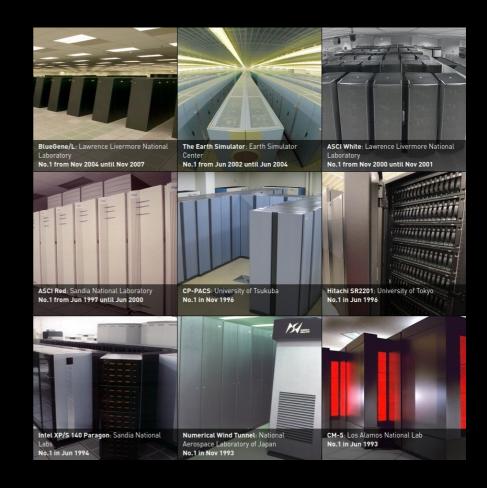
2022 GeForce RTX3090Ti peak is 40 TFLOPS @ \$2K (not counting host)... \$0.05 / GFLOPS

A Lesson From http://top500.org



#1 Machines, http://top500.org





Now: 11,039,616 cores, 1.742 **EFLOPS**, 30**MW**

The Future

- Everything is moving down...

 Your cell phone outruns the 1992 MasPar MP1;
 supercomputer today, in your cell phone soon
- More parallelism (and maybe quantum too?)
- More heterogeneous (helped by dark silicon)
- Everything contains a connected computer (e.g., IoT: Internet of Things)... a good thing?