

Pipelined Design

CPE380, Spring 2022

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<http://aggregate.org/hankd/>

Different Implementations

- **Multi-cycle** MIPS, **multiple CPI**:

<http://aggregate.org/EE380/multiv.html>

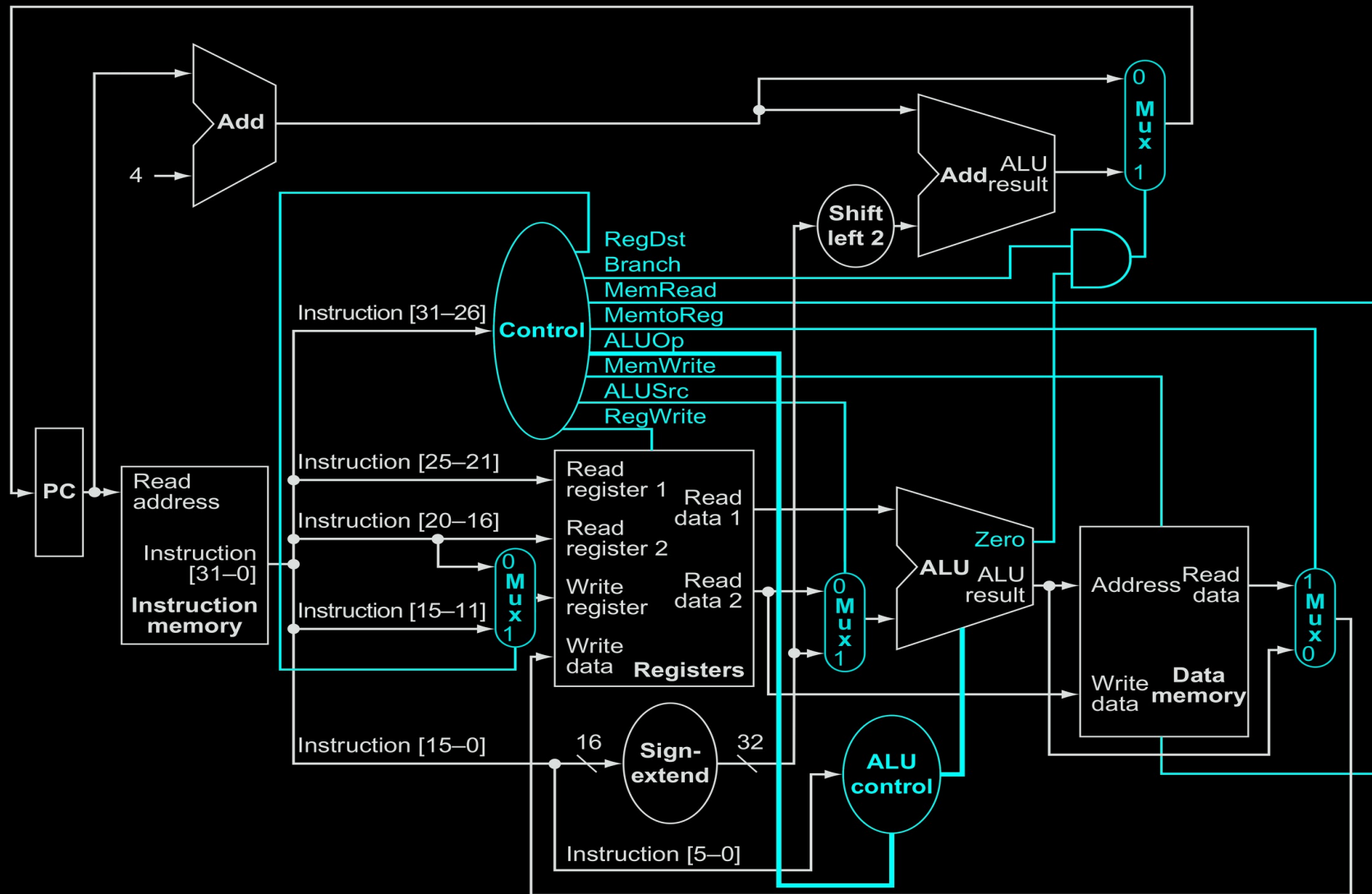
- **Single-cycle** MIPS, **1 CPI**, but **slow clock**:

<http://aggregate.org/EE380/onebeq.html>

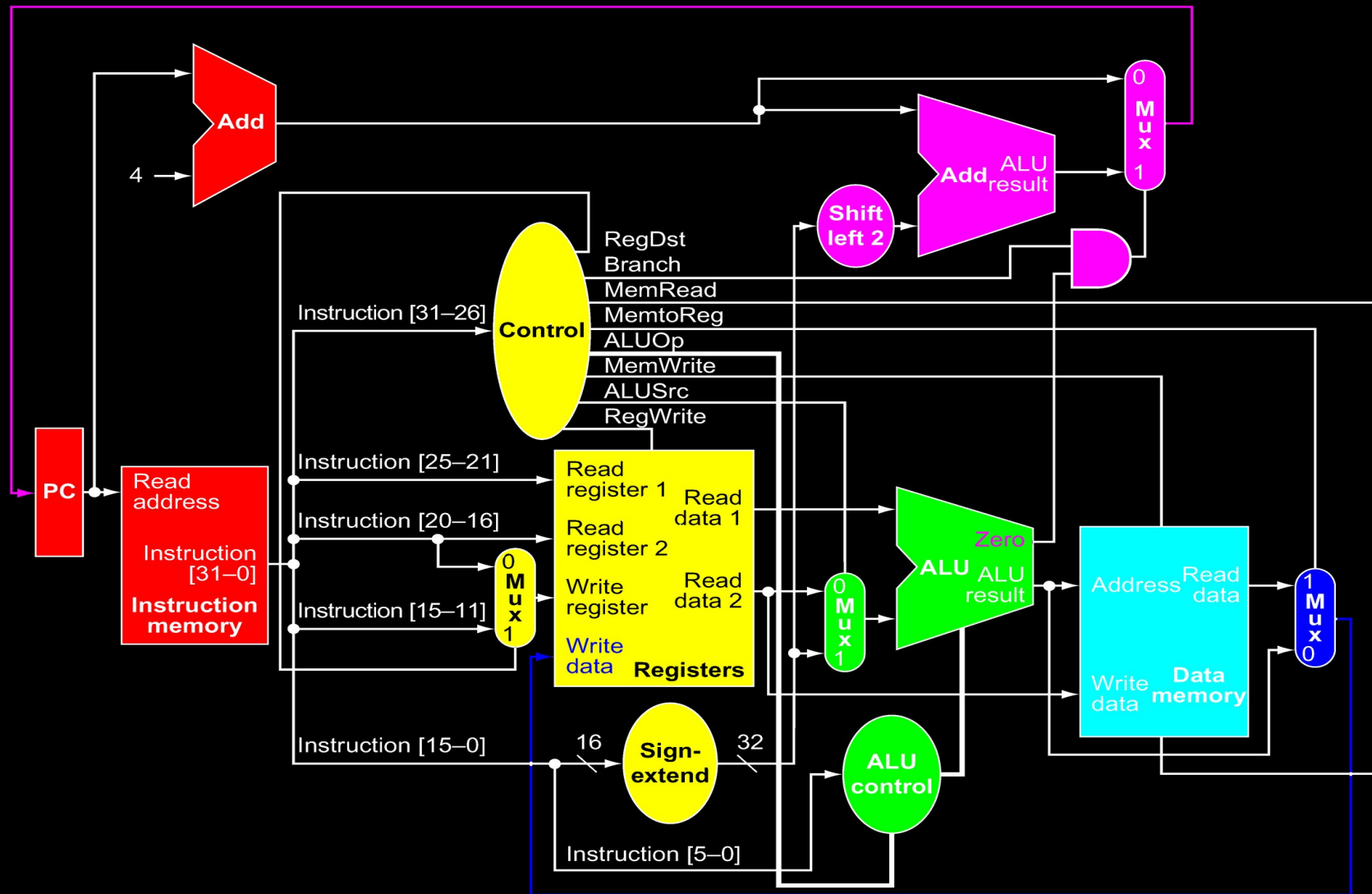
- **Pipelined** MIPS, multiple CPI, but **fast clock** and **throughput** up to **1 instruction/cycle**

Basic Pipelining

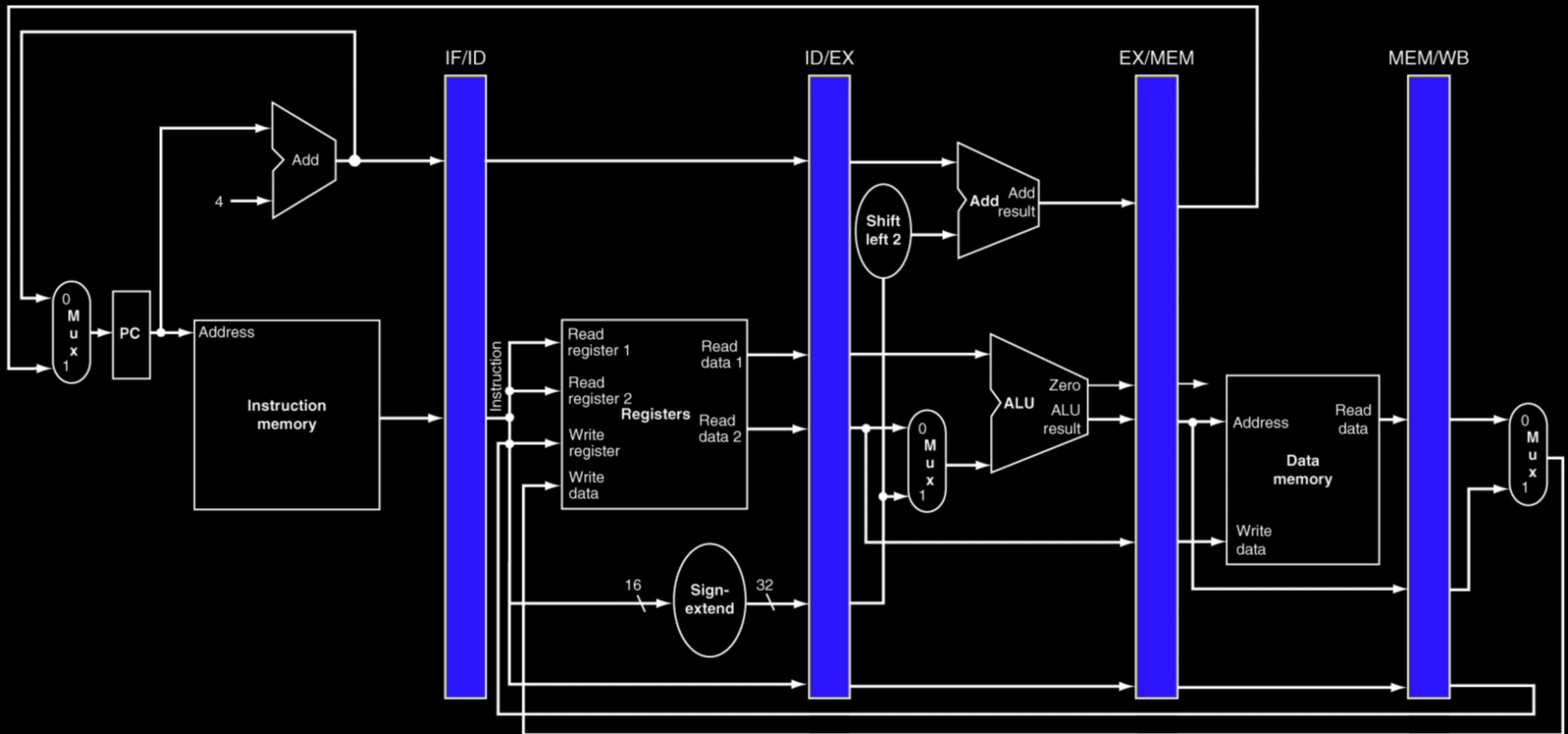
- Single-cycle **control signals move through the pipe** along with the data
- Divide single-cycle design into **equal-delay stages**, adding **buffers between stages**
 - Ideally, n stages gives nX throughput
 - Usually $< nX$, and n can't be arbitrarily large
- Throughput comes from having useful work in all stages all the time – avoiding **bubbles**



The single cycle design...



IF: Instruction Fetch **EX:** Execute **WB:** Write Back
ID: Instruction Decode **MEM:** Memory Access **what is this?**



- Add buffers between pipe stages...

Pipeline Throughput

IF	ID	EX	MEM	WB
addu \$t0,\$t1,\$t2				—
	addu \$t0,\$t1,\$t2			—
		addu \$t0,\$t1,\$t2		—
			addu \$t0,\$t1,\$t2	—
and \$t3,\$t4,\$t5				addu \$t0,\$t1,\$t2
	and \$t3,\$t4,\$t5			—
		and \$t3,\$t4,\$t5		—
			and \$t3,\$t4,\$t5	—
				and \$t3,\$t4,\$t5
...				

IF	ID	EX	MEM	WB
addu \$t0,\$t1,\$t2				—
and \$t3,\$t4,\$t5	addu \$t0,\$t1,\$t2			—
addiu \$t6,\$0,1	and \$t3,\$t4,\$t5	addu \$t0,\$t1,\$t2		—
lw \$t7,0(\$t8)	addiu \$t6,\$0,1	and \$t3,\$t4,\$t5	addu \$t0,\$t1,\$t2	—
sw \$t1,4(\$t9)	lw \$t7,0(\$t8)	addiu \$t6,\$0,1	and \$t3,\$t4,\$t5	addu \$t0,\$t1,\$t2
beq \$t1,\$t2,lab	sw \$t1,4(\$t9)	lw \$t7,0(\$t8)	addiu \$t6,\$0,1	and \$t3,\$t4,\$t5
...	beq \$t1,\$t2,lab	sw \$t1,4(\$t9)	lw \$t7,0(\$t8)	addiu \$t6,\$0,1
...	...	beq \$t1,\$t2,lab	sw \$t1,4(\$t9)	lw \$t7,0(\$t8)
...	...	...	beq \$t1,\$t2,lab	sw \$t1,4(\$t9)
...	...	...	...	beq \$t1,\$t2,lab

Pipeline Bubble: nop

IF

ID

EX

MEM

WB

```
addu $t0,$t1,$t2
and $t3,$t4,$t5
addiu $t6,$0,1
lw $t7,0($t8)
sw $t1,4($t9)
beq $t1,$t2,lab
...
...
...
...
```

```
addu $t0,$t1,$t2
and $t3,$t4,$t5
addiu $t6,$0,1
lw $t7,0($t8)
sw $t1,4($t9)
beq $t1,$t2,lab
...
...
...
...
```

```
addu $t0,$t1,$t2
and $t3,$t4,$t5
addiu $t6,$0,1
lw $t7,0($t8)
sw $t1,4($t9)
beq $t1,$t2,lab
...
...
...
...
```

```
addu $t0,$t1,$t2
and $t3,$t4,$t5
addiu $t6,$0,1
lw $t7,0($t8)
sw $t1,4($t9)
beq $t1,$t2,lab
...
```

```
-
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addu $t0,$t1,$t2
and $t3,$t4,$t5
addiu $t6,$0,1
lw $t7,0($t8)
sw $t1,4($t9)
beq $t1,$t2,lab
```

IF

ID

EX

MEM

WB

```
addu $t0,$t1,$t2
and $t3,$t4,$t5
addiu $t6,$0,1
lw $t7,0($t8)
sw $t1,4($t7)
beq $t1,$t2,lab
beq $t1,$t2,lab
beq $t1,$t2,lab
beq $t1,$t2,lab
...
...
...
...
```

```
addu $t0,$t1,$t2
and $t3,$t4,$t5
addiu $t6,$0,1
lw $t7,0($t8)
sw $t1,4($t7)
sw $t1,4($t7)
sw $t1,4($t7)
sw $t1,4($t7)
beq $t1,$t2,lab
...
...
...
...
```

```
addu $t0,$t1,$t2
and $t3,$t4,$t5
addiu $t6,$0,1
lw $t7,0($t8)
nop
nop
nop
sw $t1,4($t7)
beq $t1,$t2,lab
...
...
...
...
```

```
addu $t0,$t1,$t2
and $t3,$t4,$t5
addiu $t6,$0,1
lw $t7,0($t8)
nop
nop
nop
nop
sw $t1,4($t7)
beq $t1,$t2,lab
...
```

```
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addu $t0,$t1,$t2
and $t3,$t4,$t5
addiu $t6,$0,1
lw $t7,0($t8)
nop
nop
nop
nop
sw $t1,4($t7)
beq $t1,$t2,lab
```


Setting The Stages

Instruction	IF	ID	EX	MEM	WB	Circuit delay
addu	250	100	300	–	100	750ps
and	250	100	100	–	100	550ps
addiu	250	100	300	–	100	750ps
lw	250	100	300	250	100	1000ps
sw	250	100	300	100	100	850ps
beq	250	100	300	–	–	750ps

- Single-cycle limited by **lw** to **1GHz clock**
- 5-stage pipeline limited by **EX**
 - 300ps latency might allow **3.33GHz** clock
 - If buffer between stages is 100ps, **2.5GHz**
- Multi-cycle might be **5 cycles @2.5GHz**

Why A Bubble?

- **Structural hazards**: can't do 2 things on one unit of HW simultaneously – **single-cycle cures this!**
- **Data dependence**: need results from previous computations, which might not be done yet
- **Control dependence**
 - Computation of branch target address
 - Conditional branch/jump taken vs. not taken

Dependence Analysis

- **Use or R**: reads the value bound to a name
- **Def or W**: binds a new value to a name
- **True dependence**: carries a value, $D \rightarrow U$, RAW
add $\$t0, \$t1, \$t2$ or $\$t3, \$t0, \$t4$
- **Anti-dependence**: kills a value, $U \leftarrow D$, WAR
add $\$t0, \$t1, \$t2$ or $\$t1, \$t3, \$t4$
- **Output dependence**: kills a value, $D \rightarrow D$, WAW
add $\$t0, \$t1, \$t2$ or $\$t0, \$t3, \$t4$

When Dependence Matters

- True dependence causes a delay

```
add $t0, $t1, $t2  
or  $t3, $t0, $t4    //wait for $t0
```

- Other types don't

How To Handle Dependence

- Have programmer/assembler **pad with NOPs**
 - **Violates ISA concept** (how much padding?); too little padding gives wrong answers, too much wastes time
 - **Makes program bigger**

IF	ID	EX	MEM	WB
add \$t0, \$t1, \$t2	...	...	...	...
nop	add \$t0, \$t1, \$t2	...	...	...
nop	nop	add \$t0, \$t1, \$t2	...	...
nop	nop	nop	add \$t0, \$t1, \$t2	...
or \$t3, \$t0, \$t4	nop	nop	nop	add \$t0, \$t1, \$t2
...	or \$t3, \$t0, \$t4	nop	nop	nop
...	...	or \$t3, \$t0, \$t4	nop	nop
...	...	...	or \$t3, \$t0, \$t4	nop
...	...	...	...	or \$t3, \$t0, \$t4

How To Handle Dependence

- **Hardware interlock**
 - rs or rt in ID same as dest in EX, MEM, WB
 - Detects dependence & stalls until satisfied
 - **nop** is really **or** with **side-effects disabled**:
MemRead, MemWrite, RegWrite, & Branch

IF	ID	EX	MEM	WB
add \$t0, \$t1, \$t2	...	...	...	...
or \$t3, \$t0, \$t4	add \$t0, \$t1, \$t2	...	...	...
...	or \$t3, \$t0, \$t4	add \$t0, \$t1, \$t2	...	...
...	or \$t3, \$t0, \$t4	nop	add \$t0, \$t1, \$t2	...
...	or \$t3, \$t0, \$t4	nop	nop	add \$t0, \$t1, \$t2
...	or \$t3, \$t0, \$t4	nop	nop	nop
...	...	or \$t3, \$t0, \$t4	nop	nop
...	...	...	or \$t3, \$t0, \$t4	nop
...	...	...	...	or \$t3, \$t0, \$t4

How To Handle Dependence

- **Value forwarding**: use interlock circuitry to find value & forward it to ID stage output buffer
 - ALU result ready from EX, so **NO DELAY!**
 - **lw** result ready from MEM, so **1 cycle delay**
 - Value still gets stored in register in WB
 - Works great, but adds lots of datapath...

IF	ID	EX	MEM	WB
lw \$t0, 0(\$t1)	...	...	...	...
or \$t3, \$t0, \$t4	lw \$t0, 0(\$t1)	...	...	...
...	or \$t3, \$t0, \$t4	lw \$t0, 0(\$t1)	...	...
...	or \$t3, \$t0, \$t4	nop	lw \$t0, 0(\$t1)	...
...	...	or \$t3, \$t0, \$t4	nop	lw \$t0, 0(\$t1)
...	...	...	or \$t3, \$t0, \$t4	nop
...	...	...	...	or \$t3, \$t0, \$t4

Using Dependence Information

- True dependence causes a delay

```
lw    $t0, 0($t1)
or     $t3, $t0, $t4    //wait for $t0
xor    $t5, $t6, $t7    //takes a cycle
```

- Use **code motion** or **out-of-order execution** to **execute useful instructions while waiting!**

```
lw    $t0, 0($t1)
xor    $t5, $t6, $t7    //this is free!
or     $t3, $t0, $t4    //wait for $t0
```


Reordering Instructions

- **Code motion** by compiler/assembler:
 - + Sees whole program, has time for analysis
 - Limited number of registers, imperfect info (e.g., does not know function unit details)
- **Out-of-order execution** by hardware:
 - + Perfect info, can use **register renaming** (with more registers than an instruction can name)
 - Limited to instructions buffered
- **Modern systems do both**

Computing “May Move”

- No dependence allows code to move
- Anti-dependence and output-dependence impose an ordering constraint... but renaming can remove that constraint:

add \$t0, \$t1, \$t2

or \$t1, \$t3, \$t4

becomes

add \$t0, \$t1, \$t2

or \$t1', \$t3, \$t4

add \$t0, \$t1, \$t2

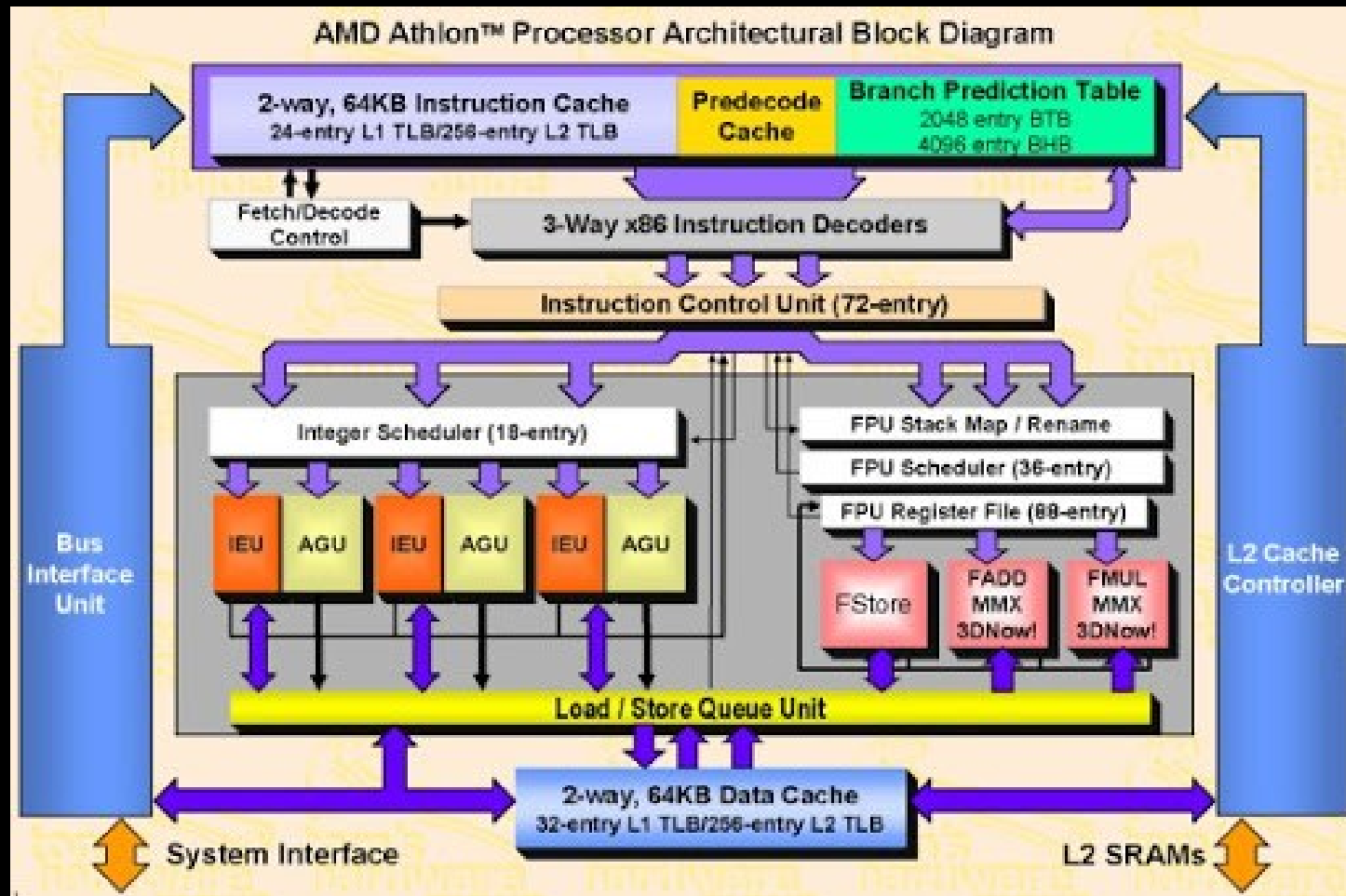
or \$t0, \$t3, \$t4

becomes

add \$t0, \$t1, \$t2

or \$t0', \$t3, \$t4

A Real Processor: AMD Athlon

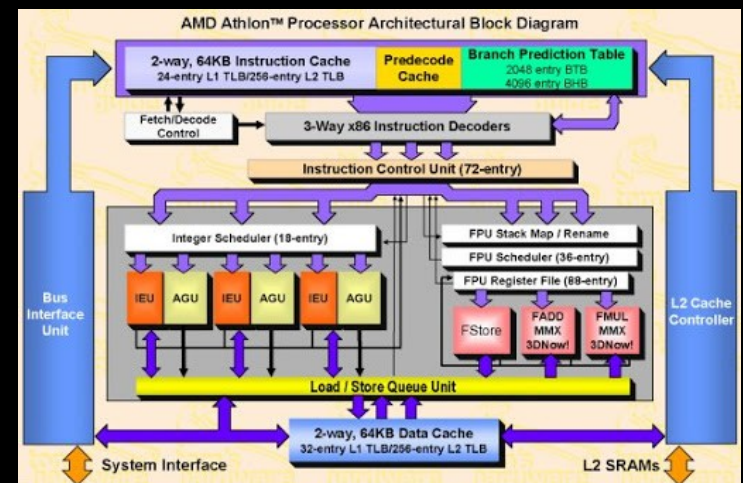


E.g., IA32 has 8 float registers, but this has 88!

Parallel Execution Orders

- IF stage can fork to feed multiple pipes
 - SIMD: GPU, SWAR, and Vector
 - VLIW: Very Long Instruction Word
 - EPIC: Explicitly Parallel Instruction Computer
 - Superscalar: instructions grouped at runtime

Athlon can sustain **3 IPC**:
3 Integer Execution Units
3 Address Generation Units
Float store, add, & multiply



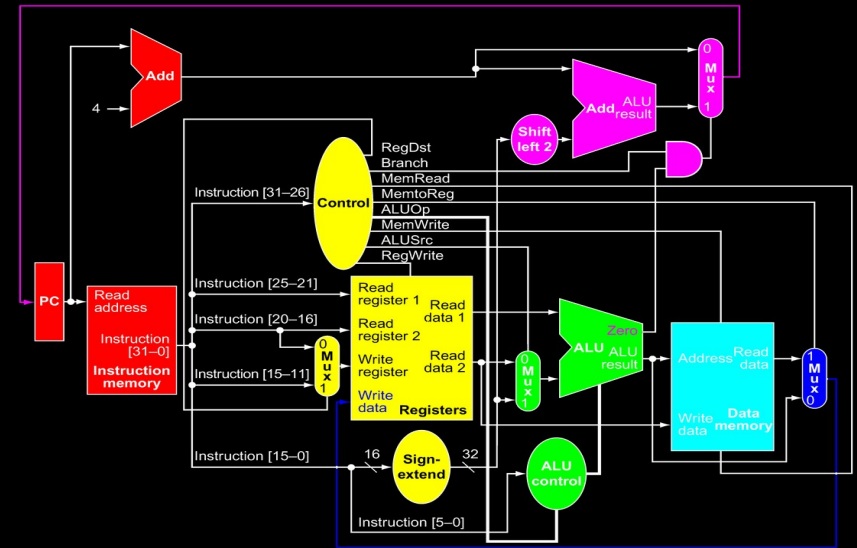
Computing The Branch Target

- Branch instructions encode offset, not address
 - Add PC + offset *typically* takes a cycle
 - What do we do while waiting for address?
- Hardware interlock & stall
- **Delayed branch**: branch *after* next instruction
- **BTB: Branch Target Buffer**
 - Caches branch {PC: target} pairs and looks 'em up at same time as fetching instruction
 - No help 1st time, but no delay on repeats

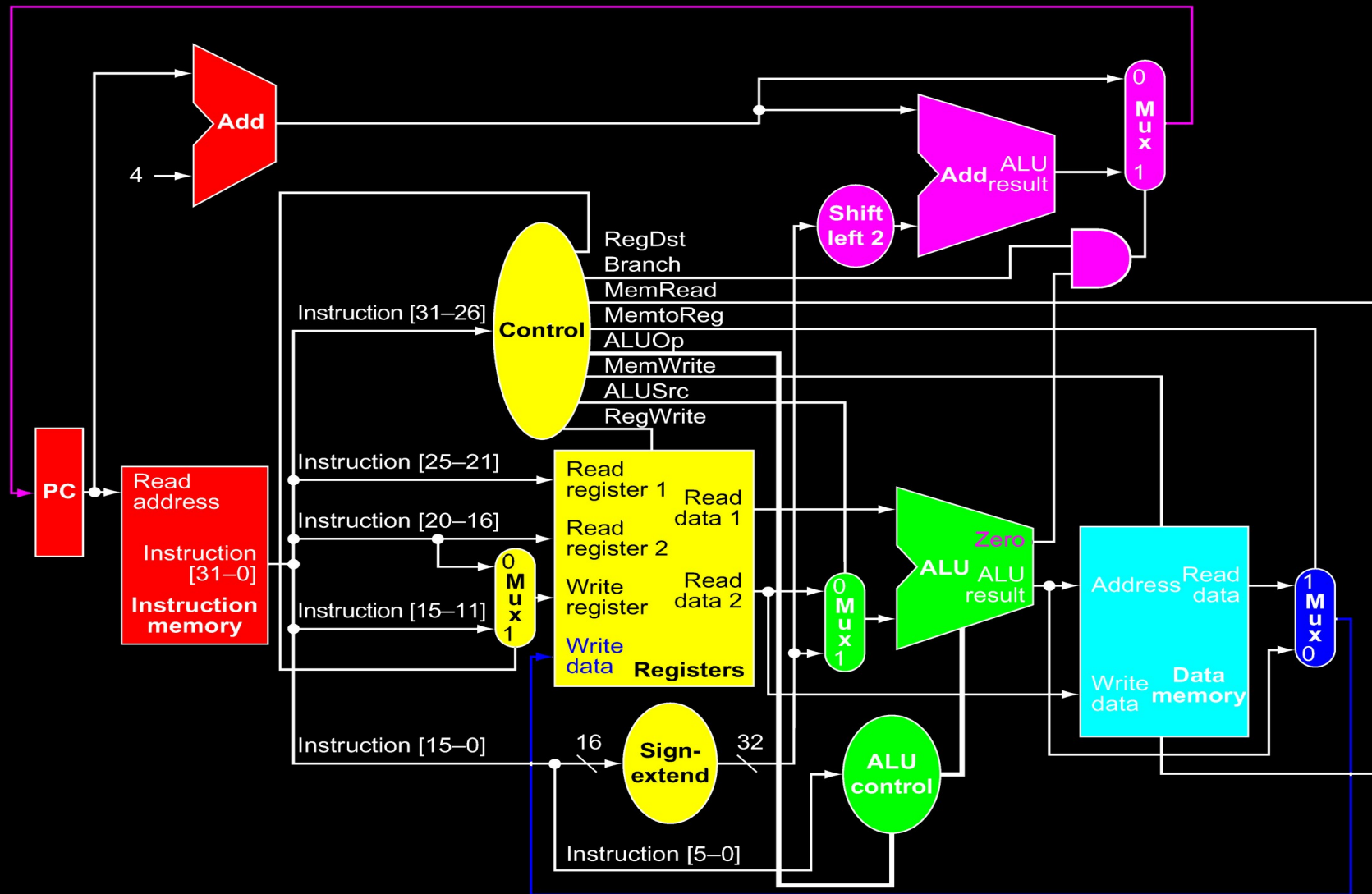
To Take, Or Not To Take?

- When do we know if conditional jump or branch is taken or not taken?

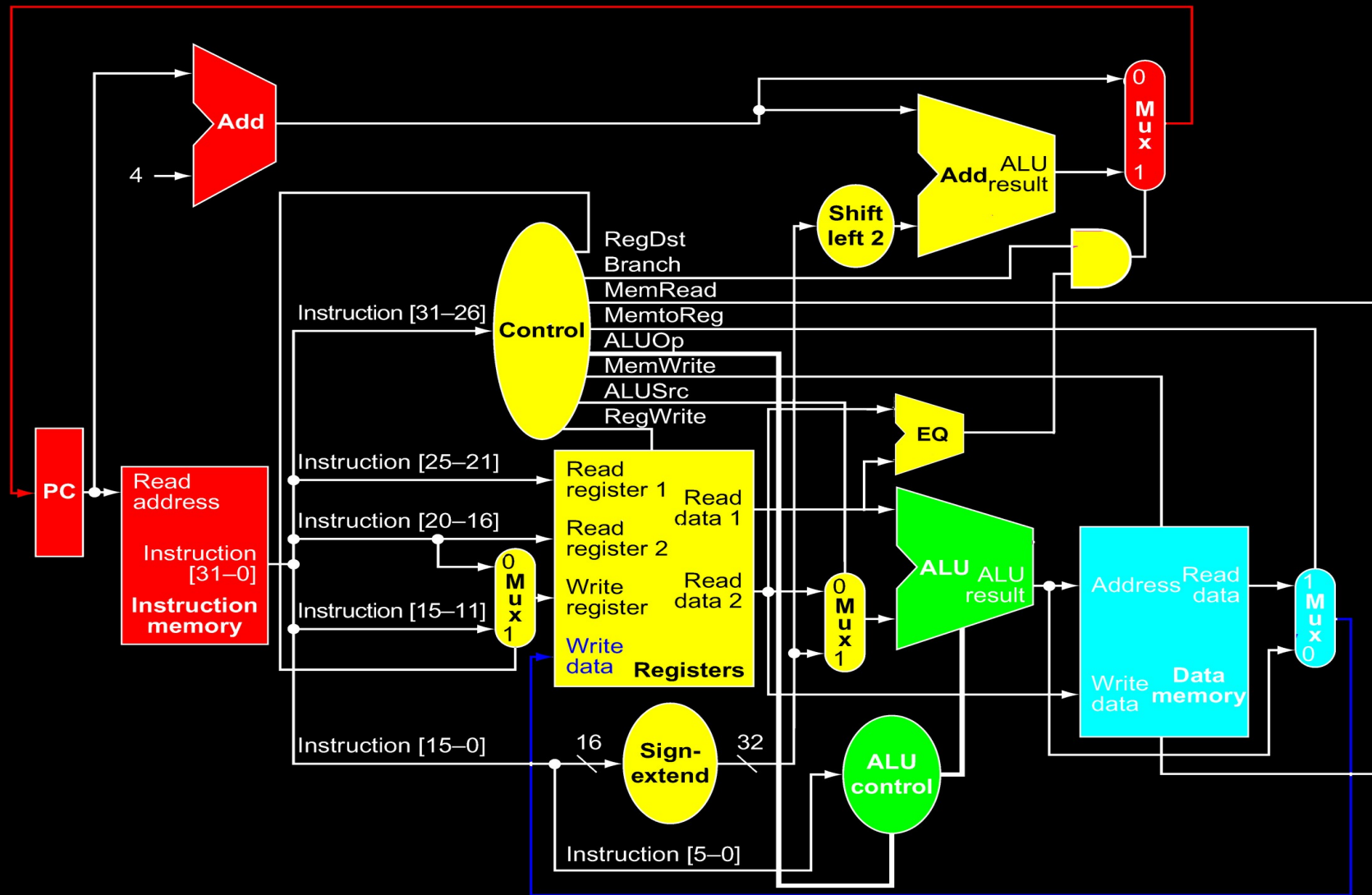
Determined only after EX stage?



- **NOP padding** or **HW interlock** very inefficient!
 - Usually determined in a late pipe stage
 - **Blocks ALL progress** (including superscalar)



IF: Instruction Fetch **EX:** Execute **WB:** Write Back
ID: Instruction Decode **MEM:** Memory Access **what is this?**



IF: Instruction Fetch **EX:** Execute **WB:** Write Back
ID: Instruction Decode **MEM:** Memory Access

Branch Prediction.

Do I Feel Lucky?



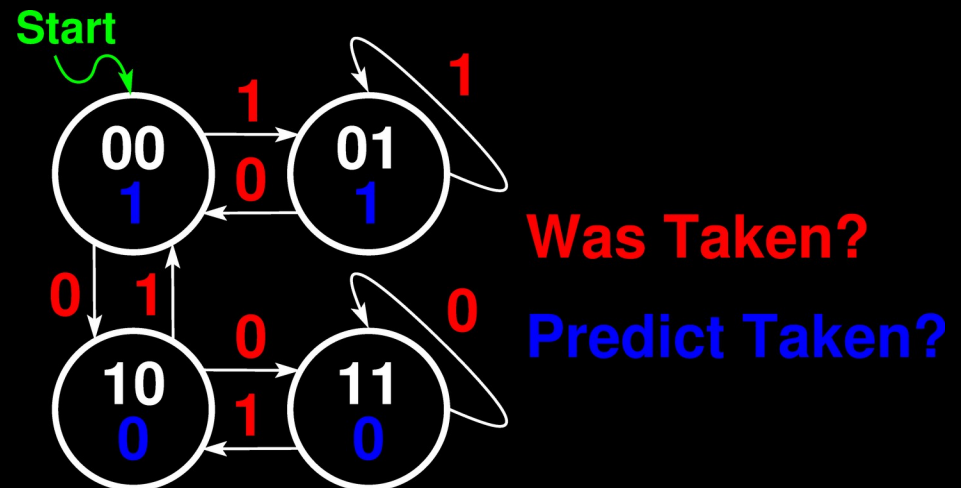
*Guess wrong and some instructions are gonna die
(well, we actually say they're **squashed**)*

- **Always not taken** – the easiest guess
- **Always taken** – more often right for do loops
- **Always BOTH not taken and taken**
 - Was tried using dual pipe of Pentium Pro
 - **Always wastes 50% of instruction fetch!**
- **Forward not, backward taken**

Those who cannot remember the past are condemned to repeat it. – *G. Santayana*

- **BHB: Branch History Buffer**
 - Jump & branch taken/not-taken “history,” but actually records a prediction state, *not* history
 - Indexed by PC; can be merged with BTB

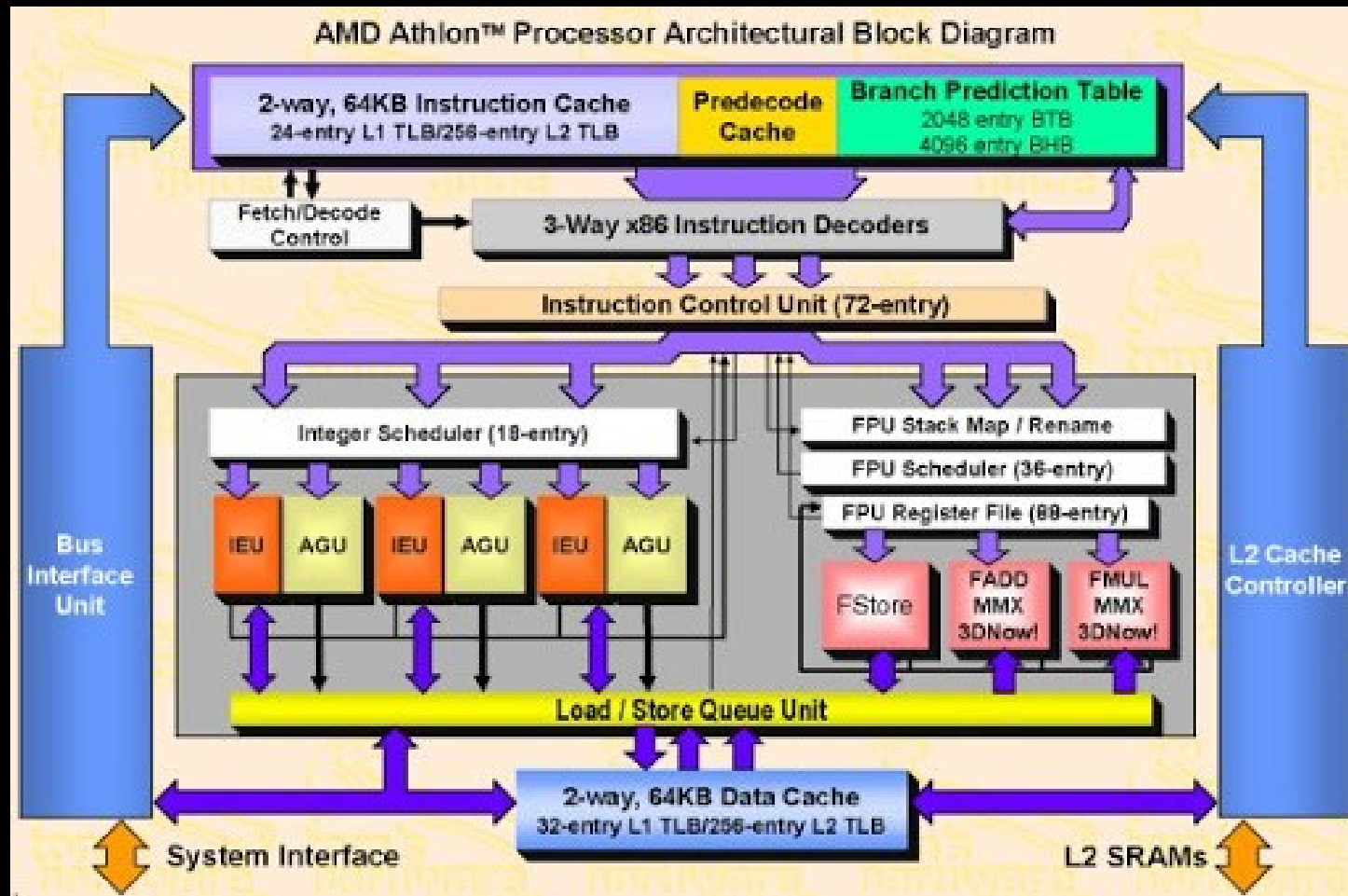
Simplest is 4-state,
just 2 bits/entry:



Fancier Prediction Methods

- Two types of prediction history recorded:
 - History of *this particular* branch/jump
 - History of *last K* branches/jumps anywhere
- More complex state machines can recognize *much* more complex patterns; also can combine multiple predictors as a **tournament predictor**
- Some systems also allow compiler hints by marking **usually taken** vs. **usually not taken**

A Real Processor: AMD Athlon



Note 2048-entry BTB and 4096-entry BHB

Verilog Implementation

- Like you'd expect:
 - Can reuse basic single-cycle design
 - Each stage becomes it's own **always**
 - Need multiple copies of some signals, one for each stage that uses them
- Not like you'd expect:
 - Some things don't follow pipe flow
 - Some non-stages should be separate things

Owner Computes

- For example, **who updates the PC?**
 - IF sets $PC = PC + 4$
 - ID sets $PC = \text{branch target}$
 - EX, MEM, or WB forces $PC = PC$ because data dependence blocks the pipe
- How to coordinate access to shared data?
 - Multiple readers is fine, with one writer
 - Could use locks, semaphores, etc.
 - Easiest is only one entity can update each:
the **owner** picks the value and is only writer

A Pipelined Verilog Version

- Organized as parallel-executing chunks for:
 - **IF** stage: reads and writes **IF_**
 - **ID** stage: reads **IF_**, writes **ID_**
 - **EX** stage: reads **ID_**, writes **EX_**
 - **MEM** stage: reads **EX_**, writes **MEM_**
 - **WB** stage: reads **MEM_**
 - Are we **running**?
 - Are mispredicted instructions **squashed**?
 - Are we **blocked** by data dependence or forwarding values?
 - Simulation **tracing** support

```

// Testbench options
define RUNTIME 200 // How long simulator can run
define CLOCK 1 // Clock transition delay
define TRACE 1 // enable simulation trace

// Types
define WORD [1:8] // size of a data word
define ADDR [1:8] // size of a memory address
define INST [1:8] // size of an instruction
define REGS [4:8] // size of a register number
define REGISTER [1:8] // register count
define MEMCNT [1:8] // memory count implemented
define OPCODE [5:8] // 6-bit opcodes
define ALUOP [1:8] // Simplified ALU codes

// Fields
define OP [1:20] // decoded field
define RS [12:21] // rs field
define RT [120:161] // rt field
define RD [12:21] // rd field
define IMM [120:161] // immediate/offset field
define SMWRT [18:6] // shift amount
define FUNC1 [5:9] // Function code (opcode extension)
define ADDRESS [12:20] // jump address field
define JPCNTR [12:20] // begin R-Warp; R-ADDR0-3; end
define JPCNTR [0,0,5,7,1] // begin R-Warp; R-ADDR0; R-RT0; R-IPW0; end
define JPCNTR [0,0,5,7,1] // begin R-Warp; R-ADDR0; R-RT0; R-Warp; R-SMWRTP; R-FUNCW0; end
define NOP 0 // null Operation is 0, $0,$0

// Instruction encoding
define RTYPE 0x000 // 00 field for all RTYPE instructions
define LTYPE 0x000 // 00 field
define ADDR0 0x000 // 00 field
define ADDR1 0x000 // 00 field
define ADDR2 0x000 // 00 field
define ADDR3 0x000 // 00 field
define ADDR4 0x000 // 00 field
define ADDR5 0x000 // 00 field
define ADDR6 0x000 // 00 field
define ADDR7 0x000 // 00 field
define ADDR8 0x000 // 00 field
define ADDR9 0x000 // 00 field
define ADDR10 0x000 // 00 field
define ADDR11 0x000 // 00 field
define ADDR12 0x000 // 00 field
define ADDR13 0x000 // 00 field
define ADDR14 0x000 // 00 field
define ADDR15 0x000 // 00 field
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define ADDR167 0x000 // 00 field
define ADDR168 0x000 // 00 field
define ADDR169 0x000 // 00 field
define ADDR170 0x000 // 00 field
define ADDR171 0x000 // 00 field
define ADDR172 0x000 // 00 field
define ADDR173 0x000 // 00 field
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define ADDR211 0x000 // 00 field
define ADDR212 0x000 // 00 field
define ADDR213 0x000 // 00 field
define ADDR214 0x000 // 00 field
define ADDR215 0x000 // 00 field
define ADDR216 0x000 // 00 field
define ADDR217 0x000 // 00 field
define ADDR218 0x000 // 00 field
define ADDR219 0x000 // 00 field
define ADDR220 0x000 // 00 field
define ADDR221
```

Color key: initialization
IF squashed **ID** blocked **EX** MEM **WB**
 debugging

[illegible]

IF: Instruction Fetch stage

- Really simple...
 - Memory is `WORD, not byte, so address>>2
 - The only thing setting IF_ir and IF_pc

```
// IF: Instruction Fetch stage
always @(posedge clk) if (running && !blocked) begin
    IF_ir <= m[(squash ? target : IF_pc) >> 2];
    IF_pc <= (squash ? target : IF_pc) + 4;
end
```

ID: Instruction Decode stage

- Decodes the instruction
- Reads from register file $r[]$
- Computes `beq` comparison & `target`

```
// ID: Instruction Decode stage
always @(posedge clk) if (running && !ID_Bad) begin
    if (blocked) ... else begin
        case (squashed `OP)
            `RTYPE: begin
                case (squashed `FUNCT)
                    `ADDU:    begin RegDst=1; Branch=0; MemRead=0;
                                ALUOp=`ALUADD; MemWrite=0; ALUSrc=0;
                                RegWrite=1; Bad=0; end
                ... endcase ... endcase
            ... ID_s <= s; ID_t <= t; ... ID_ALUOp <= ALUOp; ...
        end end
```

EX: Execute stage

- Contains the ALU for integers & addresses

```
// EX: EXecute stage
always @(posedge clk) if (running) begin
    case (ID_ALUOp)
        `ALUAND: alu = ID_s & ID_src;
        `ALUOR:  alu = ID_s | ID_src;
        `ALUADD: alu = ID_s + ID_src;
        `ALUSUB: alu = ID_s - ID_src;
        `ALUSLT: alu = ID_s < ID_src;
        `ALUXOR: alu = ID_s ^ ID_src;
        default: alu = (ID_src << 16);
    endcase
    EX_alu <= alu;
    EX_t <= ID_t;
    EX_rd <= ID_rd;
    EX_MemRead <= ID_MemRead;
    EX_MemWrite <= ID_MemWrite;
    EX_Bad <= ID_Bad;
end
```

MEM: MEMory access stage

- Does a memory read or write
- Uses **EX_MemRead** for both read and mux **v**

```
// MEM: data MEMory access stage
always @(posedge clk) if (running) begin
    if (EX_MemRead) v = m[EX_alu >> 2]; else v = EX_alu;
    if (EX_MemWrite) m[EX_alu >> 2] <= EX_t;

    MEM_v <= v;
    MEM_rd <= EX_rd;
    MEM_Bad <= EX_Bad;
end
```

WB: Write Back stage

- Writes result into register...
 - Register \$0 is read only
 - Not writing? Say we write to register 0...
- An instruction isn't done until it's here, so this is where halting really happens

```
// WB: register Write Back stage
always @(posedge clk) if (running) begin
    if (MEM_rd) r[MEM_rd] <= MEM_v;
    if (MEM_Bad) halt <= 1;
end
```

Running?

- Enables normal operation of stages
- Not running normally if:
 - Halted
 - There's a reset in progress; reset writes into stuff it doesn't own, so we need owners off

```
// Running state?  
wire running;  
assign running = ((!halt) && (!reset));
```

Squashed?

- For `beq`, we'll predict `not taken`, so `IF_pc+4`
- If we were right, no bubble
- If wrong, need to squash fetched instructions
 - `No side-effects to undo yet`
 - Just convert into ``NOP` to `prevent future s-e`

```
`define NOP `OR    // Null Operation is or $0,$0,$0
```

```
// Squash instruction fetched on a mispredicted branch  
wire `INST squashed;  
assign squashed = (squash ? `NOP : IF_ir);
```


Simulation Tracing

- Yet another (complex!) parallel-executing thing:

```
// State-by-state trace
`ifdef TRACE
always @(posedge clk) if (running) begin
    ...
    $display("IF ir=%x pc=%1d", IF_ir, IF_pc);
    case (IF_ir `OP)
        `RTYPE: begin
            case (IF_ir `FUNCT)
                `ADDU: $display("IF addu $%1d,$%1d,$%1d",
                               IF_ir `RD, IF_ir `RS, IF_ir `RT); ...
            endcase
        endcase
    if (ID_Bad) $display("ID illegal instruction");
    else $display("ID s=%1d t=%1d src=%1d rd=%1d
                  MemRead=%b ALUOp=%b MemWrite=%b", ID_s, ID_t,
                  ID_src, ID_rd, ID_MemRead, ID_ALUOp, ID_MemWrite);
    ...
end
`endif
endmodule
```

Color key: initialization
IF squashed ID blocked EX MEM WB
debugging

[illegible]

Three Verilog Implementations

- **Multi-cycle** MIPS, **multiple CPI**:

<http://aggregate.org/EE380/multiv.html>

- **Single-cycle** MIPS, **1 CPI**, but **slow clock**:

<http://aggregate.org/EE380/onebeq.html>

- **Pipelined** MIPS, **fast clock**, **~1 CPI throughput**:

<http://aggregate.org/EE380/pipe.html>

Out-Of-Order Implementation?

- *Beyond the scope of this class*, but it's **dataflow**
- CDC6600 **Scoreboard**
 - Need **both operands in registers**
 - Instruction **waits @ function unit**
- **Tomasulo Scheduling**
 - Copies operands **when each one is available**
 - Instruction **waits @ reservation station**
 - **Common data bus** broadcasts each result
- Now rename registers, no serial bottleneck